

Oblivious Routing and Minimum Bisection

Seminar: Approximation Algorithms

Markus Kaiser

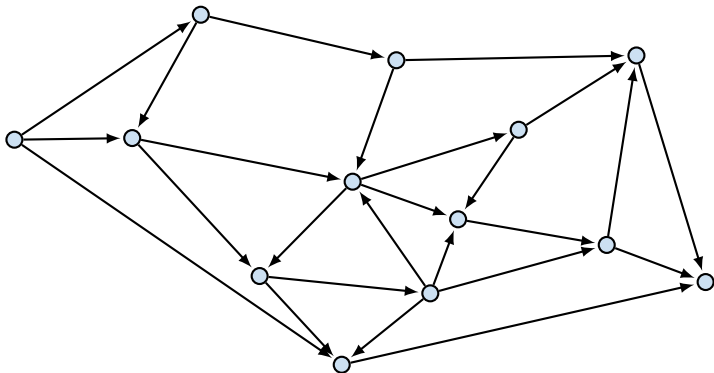
June 3, 2014

Problem (Single Commodity Flow)

Given

- An (un)directed Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$
- A source s and a target t

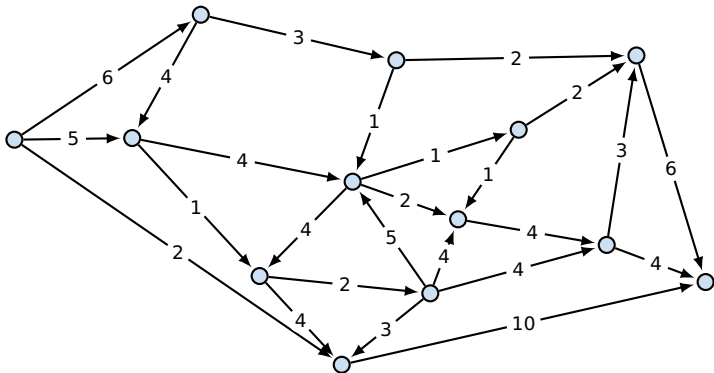
Calculate a maximum possible flow $f : E \rightarrow \mathbb{R}^+$ through G .



Problem (Single Commodity Flow)

Given

- An (un)directed Graph $G = (V, E)$
- A *capacity function* $c : E \rightarrow \mathbb{R}^+$
- A source s and a target t

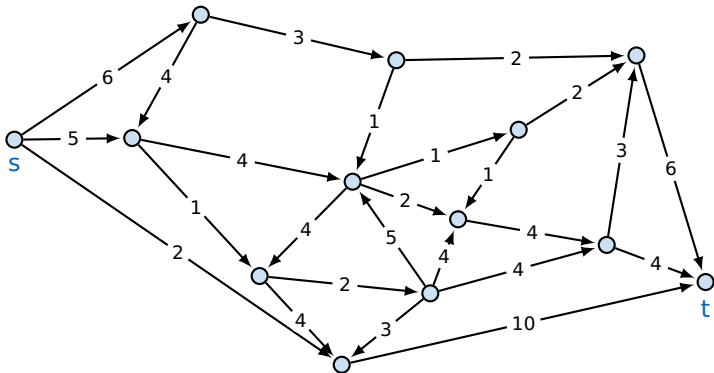
Calculate a maximum possible flow $f : E \rightarrow \mathbb{R}^+$ through G .

Problem (Single Commodity Flow)

Given

- An (un)directed Graph $G = (V, E)$
- A *capacity function* $c : E \rightarrow \mathbb{R}^+$
- A source s and a target t

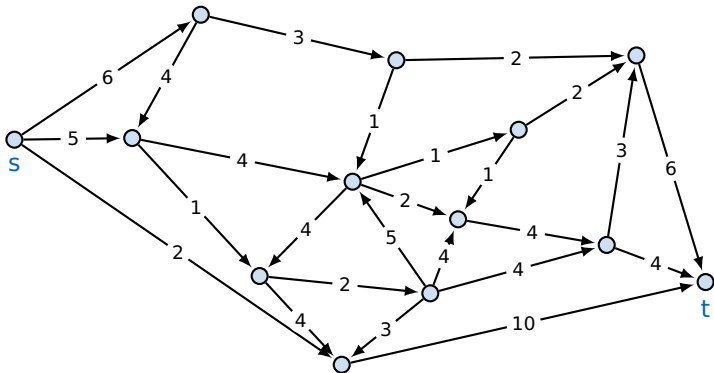
Calculate a maximum possible flow $f : E \rightarrow \mathbb{R}^+$ through G .



Problem (Single Commodity Flow)

Given

- An (un)directed Graph $G = (V, E)$
- A *capacity function* $c : E \rightarrow \mathbb{R}^+$
- A source s and a target t

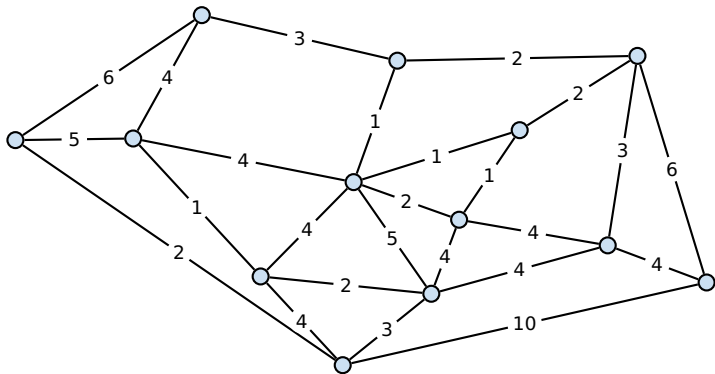
Calculate a maximum possible *flow* $f : E \rightarrow \mathbb{R}^+$ through G .

Problem (Multi Commodity Flow)

Given

- An undirected Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$
- A demand function $d : V^2 \rightarrow \mathbb{R}^+$

Calculate a flow f with least congestion $\rho = \max_{e \in E} \frac{f_e}{c_e}$.

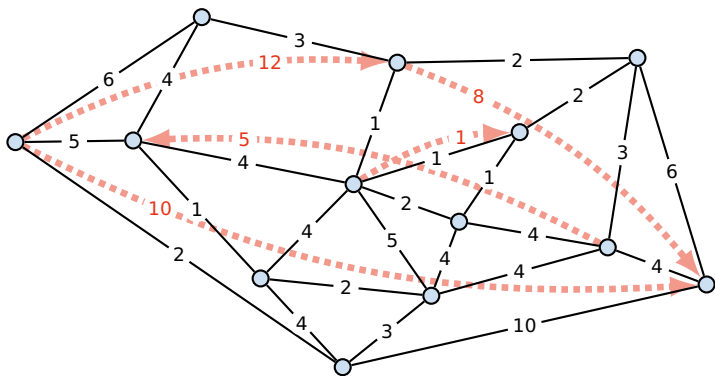


Problem (Multi Commodity Flow)

Given

- An undirected Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$
- A demand function $d : V^2 \rightarrow \mathbb{R}^+$

Calculate a flow f with least congestion $\rho = \max_{e \in E} \frac{f_e}{c_e}$.

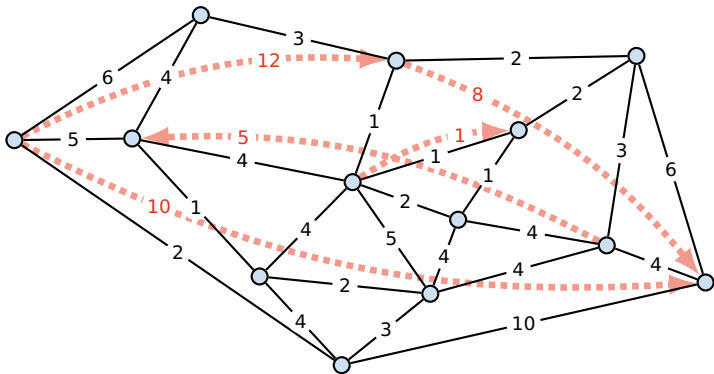


Problem (Multi Commodity Flow)

Given

- An undirected Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$
- A demand function $d : V^2 \rightarrow \mathbb{R}^+$

Calculate a flow f with least congestion $\rho = \max_{e \in E} \frac{f_e}{c_e}$.

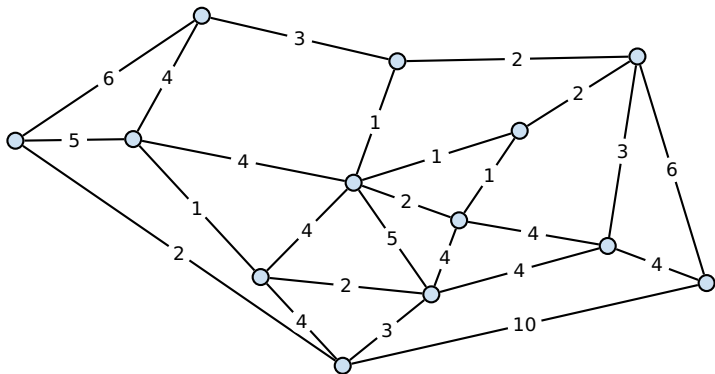


Problem (Oblivious Routing)

Given

- An undirected Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$

Calculate a combination of paths for each $(u, v) \in V^2$ such that for **any** demand function the **congestion** will be as small as possible.

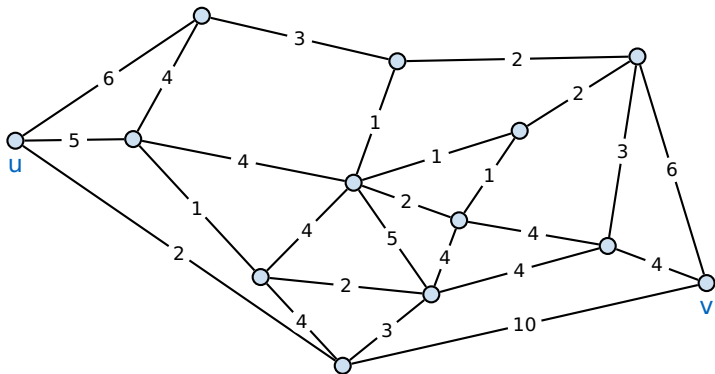


Problem (Oblivious Routing)

Given

- An undirected Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$

Calculate a combination of paths for each $(u, v) \in V^2$ such that for **any** demand function the **congestion** will be as small as possible.

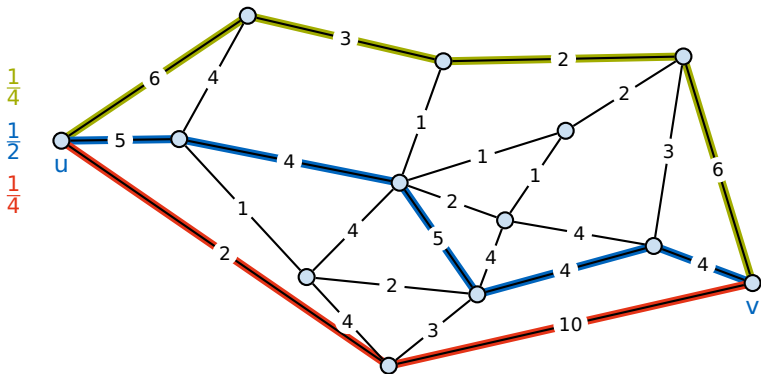


Problem (Oblivious Routing)

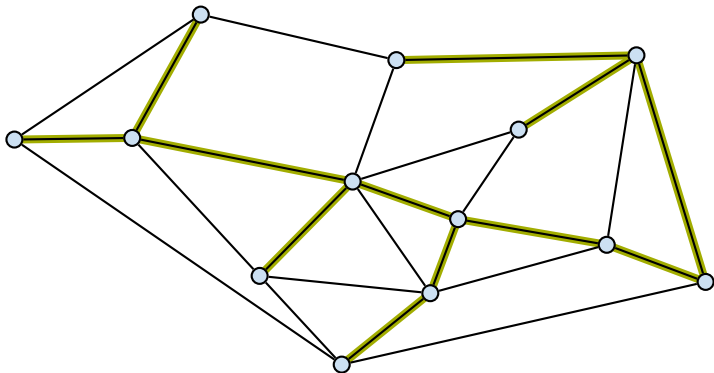
Given

- An undirected Graph $G = (V, E)$
- A capacity function $c : E \rightarrow \mathbb{R}^+$

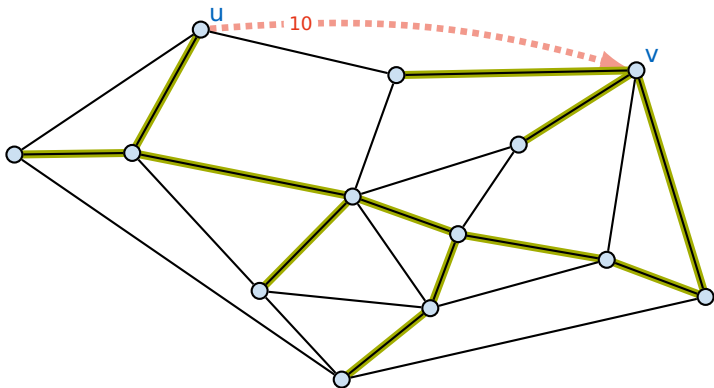
Calculate a combination of paths for each $(u, v) \in V^2$ such that for *any* demand function the *congestion* will be as small as possible.



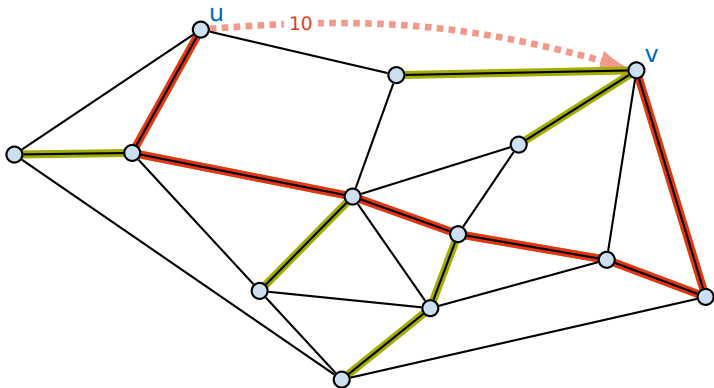
- Choose any **spanning tree** T of G
- Routing along its unique paths is a feasible solution



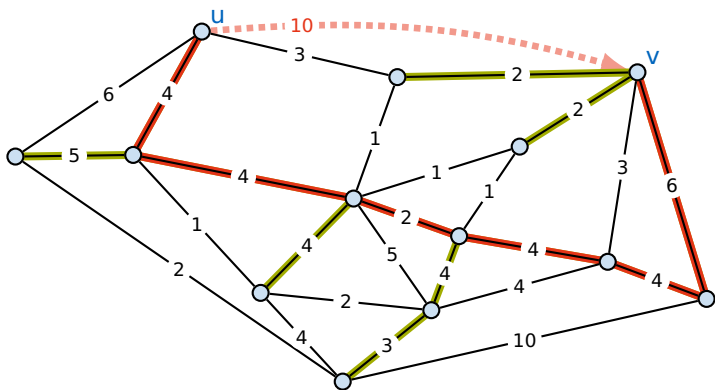
- Choose any **spanning tree** T of G
- Routing along its unique paths is a feasible solution



- Choose any **spanning tree** T of G
- Routing along its unique paths is a feasible solution



- Choose any **spanning tree** T of G
- Routing along its unique paths is a feasible solution

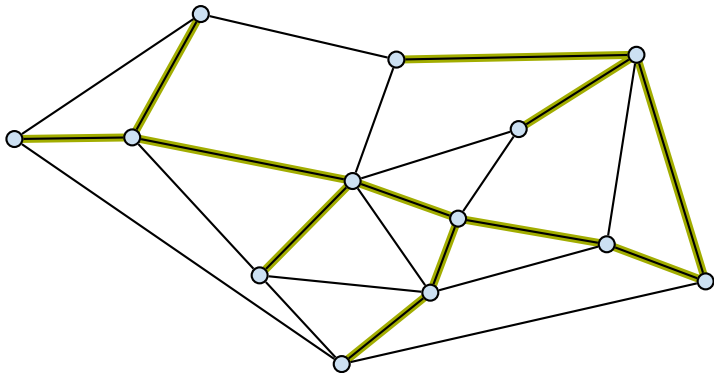


$$\rho = \max_{e \in E} \frac{f_e}{c_e} = \frac{10}{2} = 5$$

- Removing one edge e_T from a ST creates a **node partition** $S(e_T)$
- Every such partition has a **capacity** $C(e_T)$
- And a **demand** $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

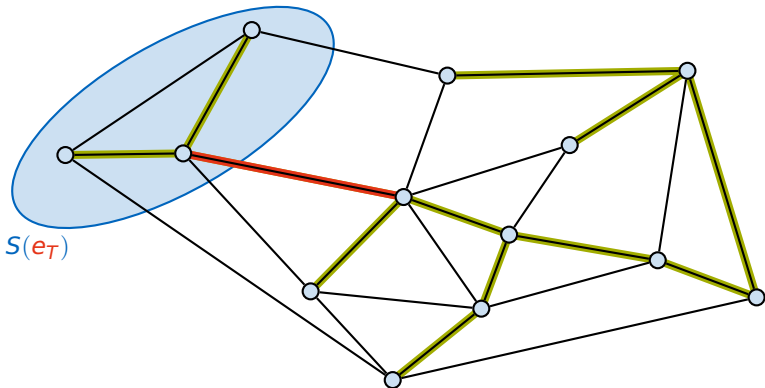
$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



- Removing one edge e_T from a ST creates a **node partition** $S(e_T)$
- Every such partition has a **capacity** $C(e_T)$
- And a **demand** $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

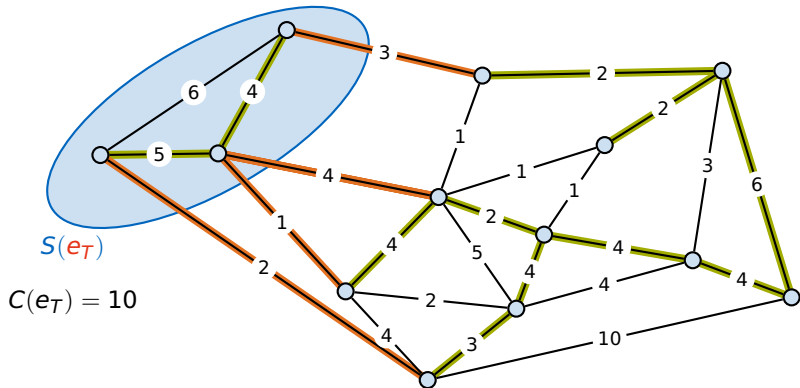
$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



- Removing one edge e_T from a ST creates a **node partition** $S(e_T)$
- Every such partition has a **capacity** $C(e_T)$
- And a **demand** $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

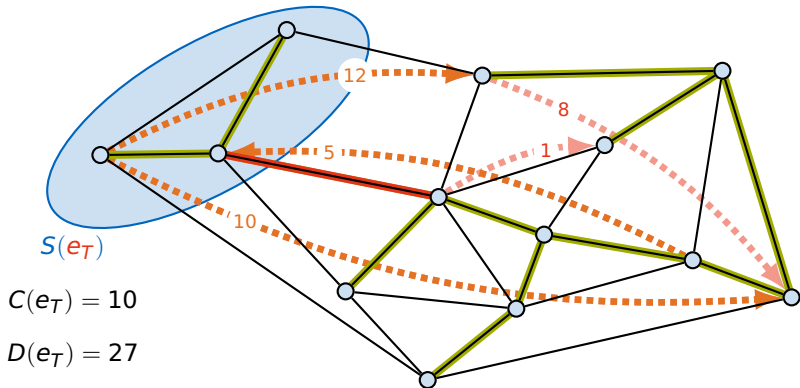
$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



- Removing one edge e_T from a ST creates a **node partition** $S(e_T)$
- Every such partition has a **capacity** $C(e_T)$
- And a **demand** $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



Lemma

For any tree T and any tree edge e_T , we know that for *any routing* in G there must be an edge with *congestion*

$$\rho_e \geq \frac{D(e_T)}{C(e_T)}$$

And therefore the *optimal solution* ρ^* can be no better.

- Suppose we find a tree such that for some α

$$\forall e_T \in E_T. \quad c_{e_T} \geq \frac{1}{\alpha} C(e_T)$$

- Then we have

$$\rho_T = \max_{e_T} \frac{D(e_T)}{c_{e_T}} \leq \alpha \max_{e_T} \frac{D(e_T)}{C(e_T)} \leq \alpha \rho^*$$

Lemma

For any tree T and any tree edge e_T , we know that for *any routing* in G there must be an edge with *congestion*

$$\rho_e \geq \frac{D(e_T)}{C(e_T)}$$

And therefore the *optimal solution* ρ^* can be no better.

- Suppose we find a tree such that for some α

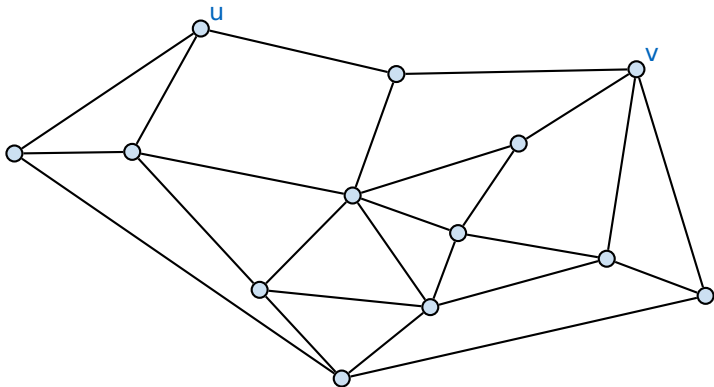
$$\forall e_T \in E_T. \quad c_{e_T} \geq \frac{1}{\alpha} C(e_T)$$

- Then we have

$$\rho_T = \max_{e_T} \frac{D(e_T)}{c_{e_T}} \leq \alpha \max_{e_T} \frac{D(e_T)}{C(e_T)} \leq \alpha \rho^*$$

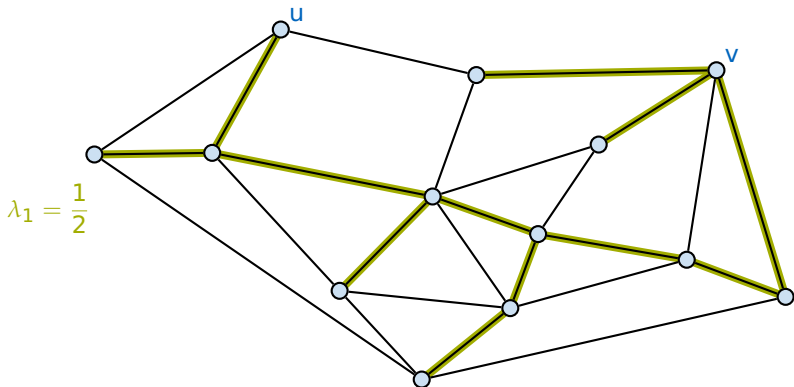
- Choose a set of spanning trees $\{T_i\}$ of G
- And a convex combination λ with $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



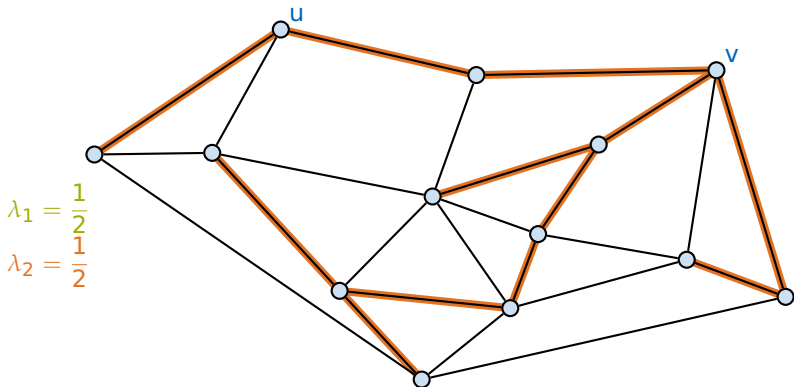
- Choose a set of spanning trees $\{T_i\}$ of G
- And a convex combination λ with $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



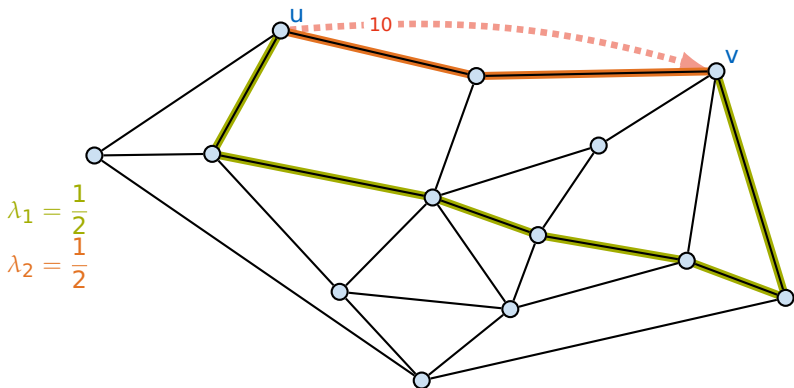
- Choose a set of spanning trees $\{T_i\}$ of G
- And a convex combination λ with $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



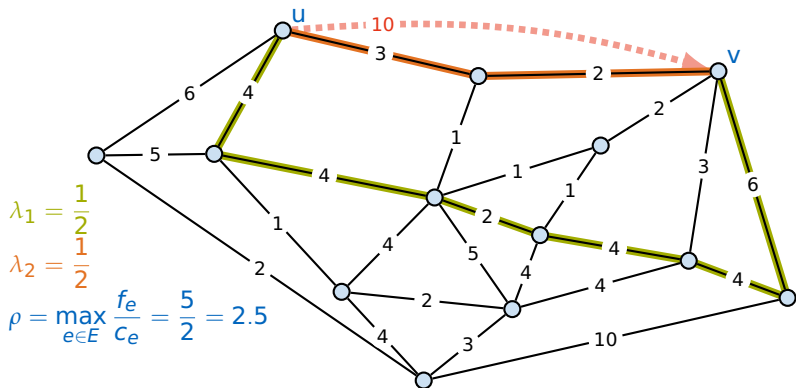
- Choose a set of spanning trees $\{T_i\}$ of G
- And a convex combination λ with $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



- Choose a set of spanning trees $\{T_i\}$ of G
- And a convex combination λ with $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



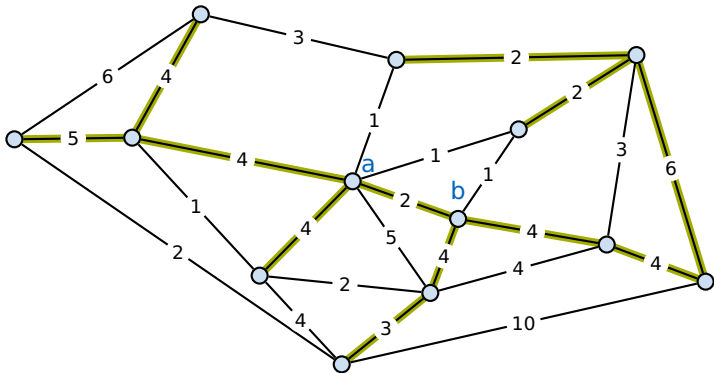
- Suppose we now find a **set of trees** such that for some α

$$\forall e \in E. \quad c_e \geq \frac{1}{\alpha} \sum_{\substack{i: \\ e \in T_i}} \lambda_i C_i(e)$$

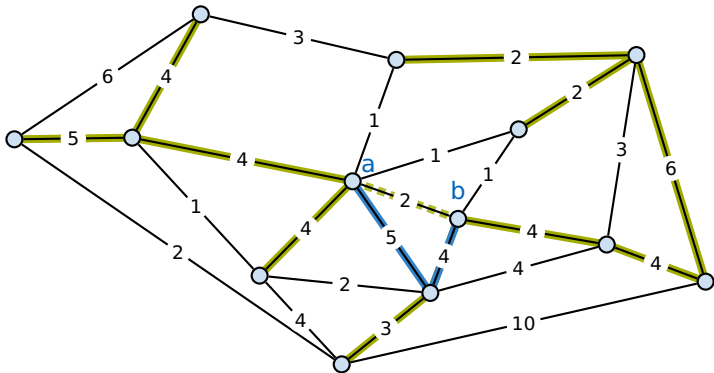
- Then we have

$$\begin{aligned} \rho &= \max_e \frac{f(e)}{c_e} \\ &= \max_e \frac{\sum_{i: e \in T_i} \lambda_i D_i(e)}{c_e} \\ &\leq \alpha \max_e \frac{\sum_{i: e \in T_i} \lambda_i D_i(e)}{\sum_{i: e \in T_i} \lambda_i C_i(e)} \\ &\leq \alpha \max_e \max_i \frac{D_i(e)}{C_i(e)} \leq \alpha \rho^* \end{aligned}$$

- Identify every edge in a tree with a **path** in G
- These paths can **overlap**
- For tree T we get a mapping $P_T : E_T \rightarrow E^+$

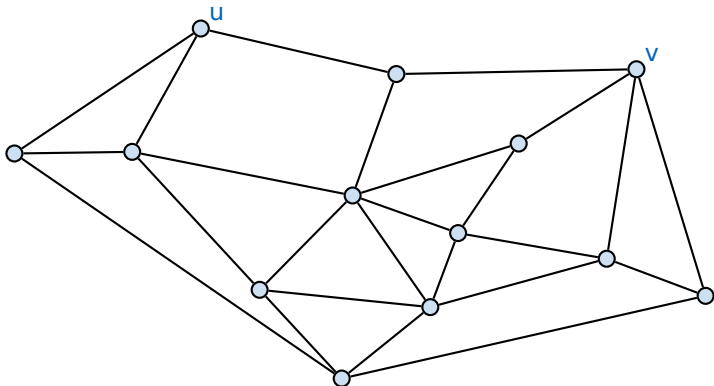


- Identify every edge in a tree with a **path** in G
- These paths can **overlap**
- For tree T we get a mapping $P_T : E_T \rightarrow E^+$



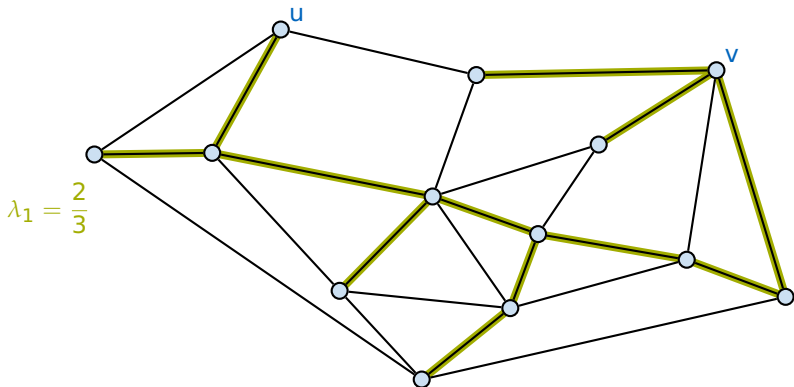
- Choose a set of pathtrees $\{T_i\}$ of G with combination λ
- Now route along the paths identified with edges. For $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



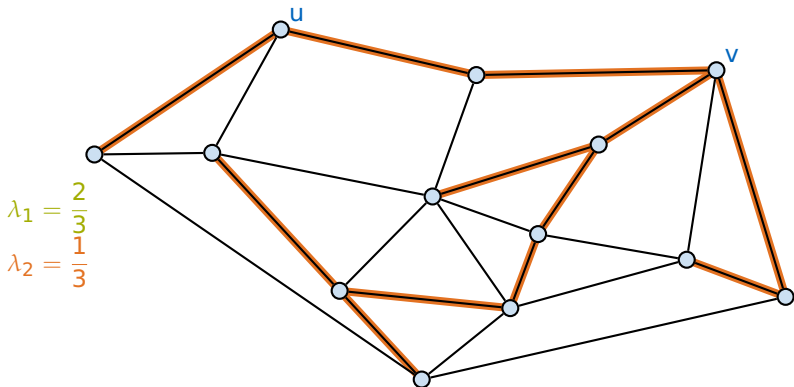
- Choose a set of pathtrees $\{T_i\}$ of G with combination λ
- Now route along the paths identified with edges. For $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



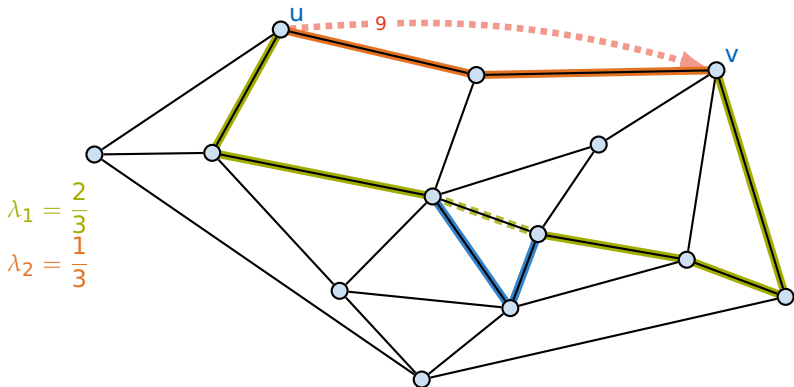
- Choose a set of pathtrees $\{T_i\}$ of G with combination λ
- Now route along the paths identified with edges. For $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



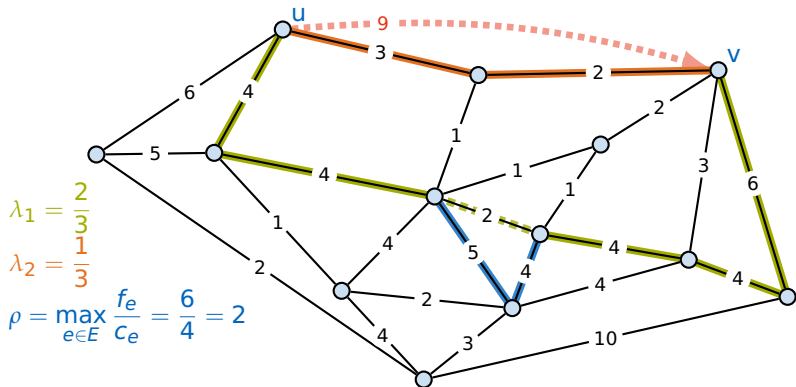
- Choose a set of pathtrees $\{T_i\}$ of G with combination λ
- Now route along the paths identified with edges. For $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



- Choose a set of pathtrees $\{T_i\}$ of G with combination λ
- Now route along the paths identified with edges. For $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



- Again suppose we now find a **set of trees** such that for some α

$$\forall e \in E. \quad c_e \geq \frac{1}{\alpha} \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)$$

- Then we have

$$\begin{aligned} \rho &= \max_e \frac{f(e)}{c_e} \\ &\leq \alpha \max_e \frac{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)}{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)} \\ &\leq \alpha \max_e \max_i \frac{D_i(e)}{C_i(e)} \leq \alpha \rho^* \end{aligned}$$

- Again suppose we now find a **set of trees** such that for some α

$$\forall e \in E. \quad c_e \geq \frac{1}{\alpha} \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)$$

- Then we have

$$\begin{aligned} \rho &= \max_e \frac{f(e)}{c_e} \\ &\leq \alpha \max_e \frac{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)}{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)} \\ &\leq \alpha \max_e \max_i \frac{D_i(e)}{C_i(e)} \leq \alpha \rho^* \end{aligned}$$

How do we find such a set of trees? How large is α ?

Primal Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.
 We want to find the best trees with smallest α .

$$\begin{aligned}
 & \min_{\alpha, \lambda} \alpha \\
 & \text{s. t. } \sum_{i \in \mathcal{I}} \lambda_i \sum_{\substack{e_T \in \mathcal{I}_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T) \leq \alpha C_{uv} \quad \forall u, v \in V \\
 & \qquad \qquad \qquad \sum_{i \in \mathcal{I}} \lambda_i = 1 \\
 & \qquad \qquad \qquad \lambda \geq 0
 \end{aligned}$$

We want to show that $\alpha \in \mathcal{O}(\log n)$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\max_{z, \mathcal{L}} z$$

$$\text{s. t. } \sum_{u,v \in V} c_{uv} l_{uv} = 1$$

$$z \leq \sum_{e_T \in \mathcal{T}_i} c_i(e_T) \sum_{(u,v) \in P_i(e_T)} l_{uv} \quad \forall i \in \mathcal{I}$$

$$\mathcal{L} \geq 0$$

If $z \in \mathcal{O}(\log n)$ then $\alpha \in \mathcal{O}(\log n)$ by strong duality

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\max_{z, \mathcal{L}} z$$

$$\text{s. t. } \sum_{u,v \in V} c_{uv} l_{uv} = 1$$

$$z \leq \sum_{e_T \in \mathcal{T}_i} C_i(e_T) \sum_{(u,v) \in P_i(e_T)} l_{uv} \quad \forall i \in \mathcal{I}$$

$$\mathcal{L} \geq 0$$

- We interpret the l_{uv} as edge lengths in G
- They define a **shortest path metric** $d_\ell(u, v)$
- For an edge $e = (x, y)$ we write $d_\ell(e) := d_\ell(x, y)$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\max_{z, \mathcal{L}} z$$

$$\text{s. t. } \sum_{u,v \in V} c_{uv} l_{uv} = 1$$

$$z \leq \sum_{e_T \in \mathcal{T}_i} c_i(e_T) \sum_{(u,v) \in P_i(e_T)} l_{uv} \quad \forall i \in \mathcal{I}$$

$$\mathcal{L} \geq 0 \quad \geq d_\ell(e_T)$$

- We interpret the l_{uv} as edge lengths in G
- They define a **shortest path metric** $d_\ell(u, v)$
- For an edge $e = (x, y)$ we write $d_\ell(e) := d_\ell(x, y)$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned}
 \max_{z, \mathcal{L}} \quad & z \\
 \text{s. t.} \quad & \sum_{u, v \in V} c_{uv} \ell_{uv} = 1 \\
 & z \leq \sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T) \quad \forall i \in \mathcal{I} \\
 & \mathcal{L} \geq 0
 \end{aligned}$$

- We interpret the ℓ_{uv} as edge lengths in G
- They define a **shortest path metric** $d_\ell(u, v)$
- For an edge $e = (x, y)$ we write $d_\ell(e) := d_\ell(x, y)$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned}
 & \max_{z, \mathcal{L}} z \\
 & \text{s. t. } \sum_{u, v \in V} c_{uv} \ell_{uv} = 1 \\
 & z \leq \sum_{e_T \in T_i} c_i(e_T) d_\ell(e_T) \quad \forall i \in \mathcal{I} \\
 & \mathcal{L} \geq 0 \qquad \qquad \qquad \geq \min_{i \in \mathcal{I}} \dots
 \end{aligned}$$

- We interpret the ℓ_{uv} as edge lengths in G
- They define a **shortest path metric** $d_\ell(u, v)$
- For an edge $e = (x, y)$ we write $d_\ell(e) := d_\ell(x, y)$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{z, \mathcal{L}} \quad & z \\ \text{s. t.} \quad & \sum_{u, v \in V} c_{uv} \ell_{uv} = 1 \\ & z \leq \min_{i \in \mathcal{I}} \sum_{e_T \in T_i} c_i(e_T) d_\ell(e_T) \\ & \mathcal{L} \geq 0 \end{aligned}$$

- We interpret the ℓ_{uv} as edge lengths in G
- They define a **shortest path metric** $d_\ell(u, v)$
- For an edge $e = (x, y)$ we write $d_\ell(e) := d_\ell(x, y)$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \sum_{e_T \in T_i} C_i(e_T) d_{\ell}(e_T) \\ \text{s. t.} \quad & \sum_{u,v \in V} c_{uv} l_{uv} = 1 \\ & \mathcal{L} \geq 0 \end{aligned}$$

- Now suppose

$$\sum_{u,v \in V} c_{uv} l_{uv} = \beta > 0$$

- If we scale every length by $\frac{1}{\beta}$ our solution will change by $\frac{1}{\beta}$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \sum_{e_T \in T_i} C_i(e_T) d_{\ell}(e_T) \\ \text{s. t.} \quad & \sum_{u,v \in V} c_{uv} l_{uv} = 1 \\ & \mathcal{L} \geq 0 \end{aligned}$$

- Now suppose

$$\sum_{u,v \in V} c_{uv} l_{uv} = \beta > 0$$

- If we scale every length by $\frac{1}{\beta}$ our solution will change by $\frac{1}{\beta}$

Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \frac{\sum_{e_T \in \mathcal{I}_i} C_i(e_T) d_\ell(e_T)}{\sum_{u,v \in V} c_{uv} \ell_{uv}} \\ \text{s.t.} \quad & \mathcal{L} \geq 0 \end{aligned}$$

- Now suppose

$$\sum_{u,v \in V} c_{uv} \ell_{uv} = \beta > 0$$

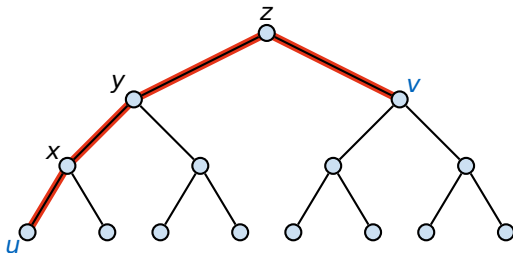
- If we scale every length by $\frac{1}{\beta}$ our solution will change by $\frac{1}{\beta}$

Theorem (Tree Metric)

For our metric d_ℓ there exists a *tree metric* (V, M) with

$$d_\ell(u, v) \leq M_{uv} \quad \forall u, v \in V$$

$$\sum_{u, v \in V} c_{uv} M_{uv} \leq \mathcal{O}(\log n) \sum_{u, v \in V} c_{uv} d_\ell(u, v)$$

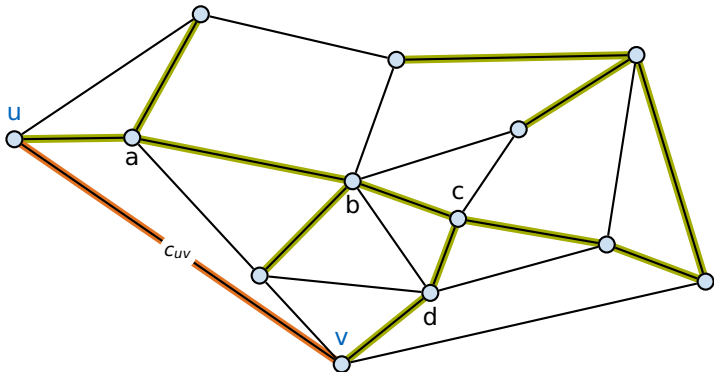


$$M_{uv} = M_{ux} + M_{xy} + M_{yz} + M_{zv}$$

Lemma

Let T be a spanning tree and (V, M) a tree metric of $G = (V, E)$. Then

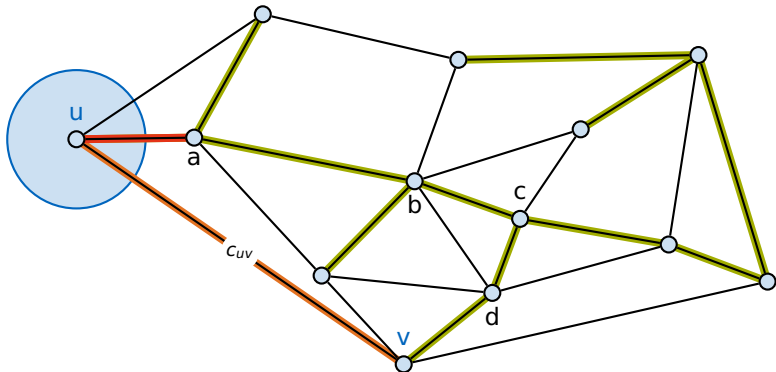
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



Lemma

Let T be a spanning tree and (V, M) a tree metric of $G = (V, E)$. Then

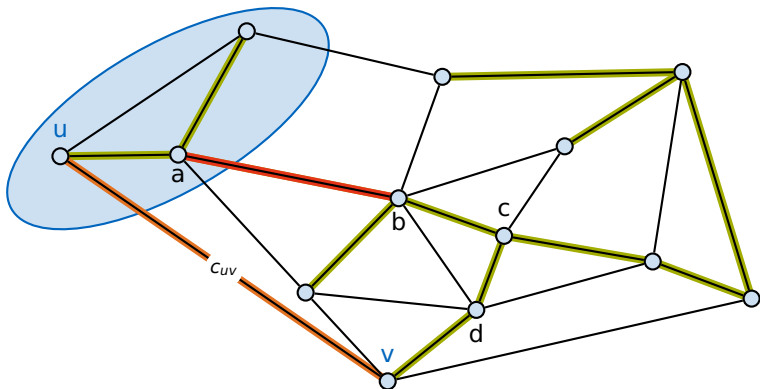
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



Lemma

Let T be a spanning tree and (V, M) a tree metric of $G = (V, E)$. Then

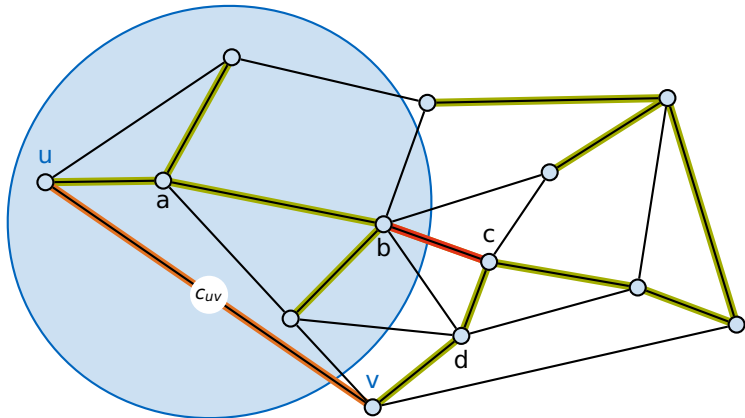
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



Lemma

Let T be a spanning tree and (V, M) a tree metric of $G = (V, E)$. Then

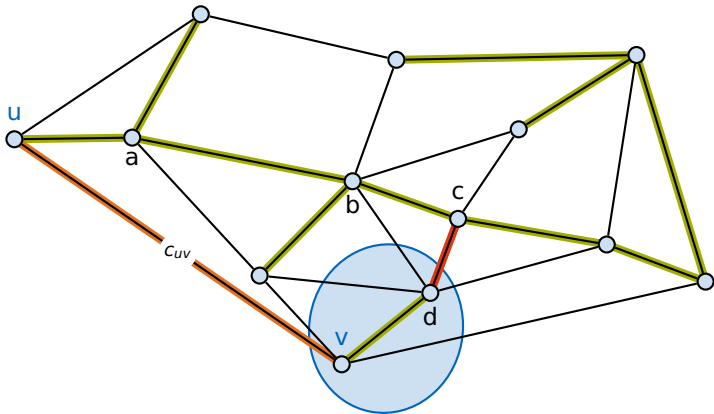
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



Lemma

Let T be a spanning tree and (V, M) a tree metric of $G = (V, E)$. Then

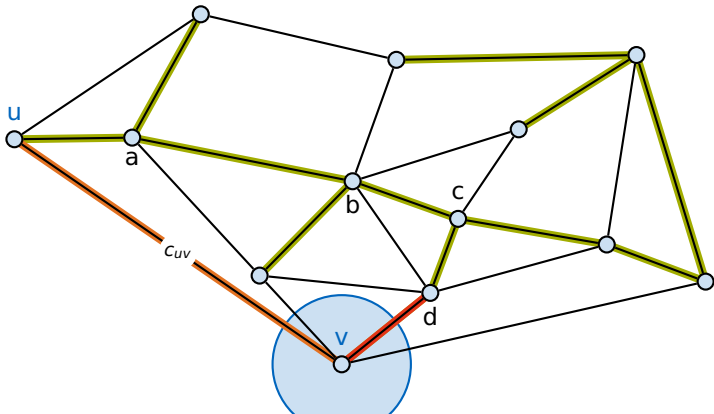
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



Lemma

Let T be a spanning tree and (V, M) a tree metric of $G = (V, E)$. Then

$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



Dual Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \frac{\sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T)}{\sum_{u, v \in V} c_{uv} \ell_{uv}} \\ \text{s. t.} \quad & \mathcal{L} \geq 0 \end{aligned}$$

For any \mathcal{L} we know that for the **minimizing tree** T_i holds

$$\begin{aligned} \sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T) &\leq \sum_{e_T \in T_i} C_i(e_T) M_{e_T} \\ &= \sum_{u, v \in V} c_{uv} M_{uv} \\ &\leq \mathcal{O}(\log n) \sum_{u, v \in V} c_{uv} d_\ell(u, v) \\ &\leq \mathcal{O}(\log n) \sum_{u, v \in V} c_{uv} \ell_{uv} \\ \frac{\sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T)}{\sum_{u, v \in V} c_{uv} \ell_{uv}} &\leq \mathcal{O}(\log n) \end{aligned}$$

Primal Program

Let \mathcal{I} be the exponentially large set of **all pathtrees**.
We want to find the best trees with smallest α .

$$\begin{aligned}
 \min_{\alpha, \lambda} \quad & \alpha \\
 \text{s. t.} \quad & \sum_{i \in \mathcal{I}} \lambda_i \sum_{\substack{e_T \in \mathcal{I}_i: \\ (u, v) \in P_i(e_T)}} C_i(e_T) \leq \alpha C_{uv} \quad \forall u, v \in V \\
 & \sum_{i \in \mathcal{I}} \lambda_i = 1 \\
 & \lambda \geq 0
 \end{aligned}$$

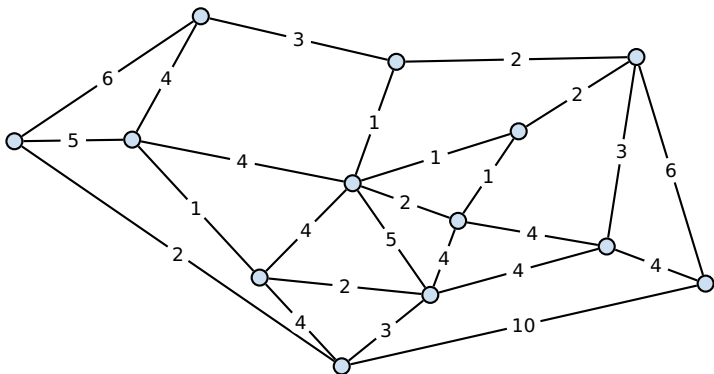
- There is a λ such that $\alpha \in \mathcal{O}(\log n)$
- Solving the LP is an $\mathcal{O}(\log n)$ -approximation
- But why are polynomially many trees enough?

Problem (Minimum Bisection)

Given

- An undirected Graph $G = (V, E)$
- A cost function $c : E \rightarrow \mathbb{R}^+$

Find a set $S \subset V$ containing half the vertices with *minimal split cost*.

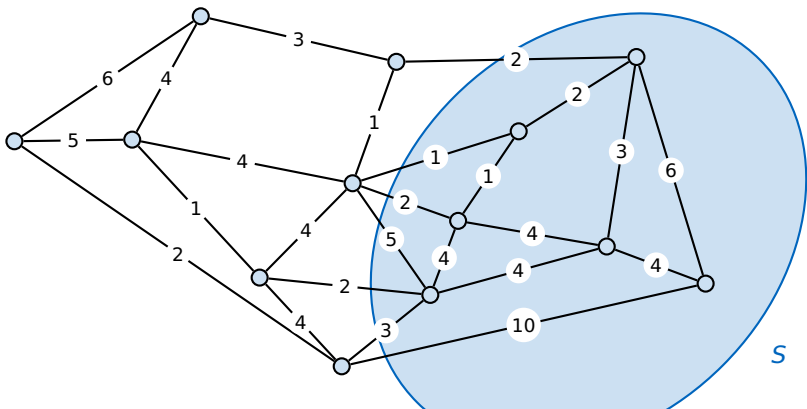


Problem (Minimum Bisection)

Given

- An undirected Graph $G = (V, E)$
- A cost function $c : E \rightarrow \mathbb{R}^+$

Find a set $S \subset V$ containing half the vertices with *minimal split cost*.

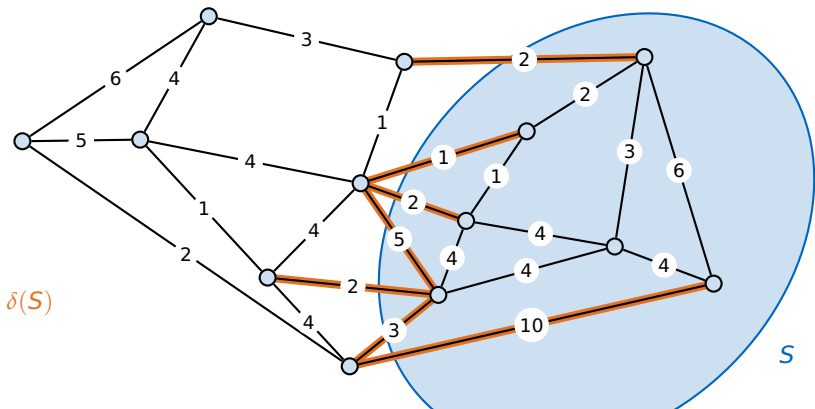


Problem (Minimum Bisection)

Given

- An undirected Graph $G = (V, E)$
- A cost function $c : E \rightarrow \mathbb{R}^+$

Find a set $S \subset V$ containing half the vertices with *minimal split cost*.

 $\delta(S)$

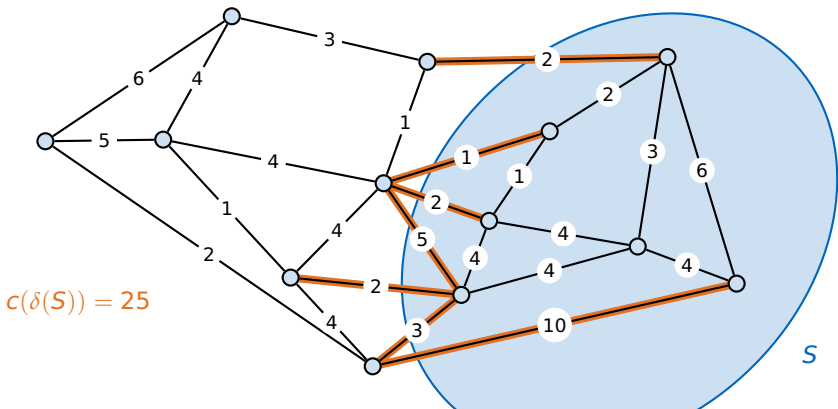
S

Problem (Minimum Bisection)

Given

- An undirected Graph $G = (V, E)$
- A cost function $c : E \rightarrow \mathbb{R}^+$

Find a set $S \subset V$ containing half the vertices with *minimal split cost*.



Minimum Bisection Approximation

Given graph $G = (V, E)$ and cost function $c : E \rightarrow \mathbb{R}^+$.

- 1 Interpret costs $c(e)$ as **capacities**
- 2 Solve oblivious routing on G , obtaining **trees** T_i
- 3 Find minimum **tree bisections** X_i for all trees T_i
- 4 Choose the X_i with **lowest** $c(\delta(X_i))$

We have to show

- What the X_i actually are
- An $\mathcal{O}(\log n)$ -**approximation** guarantee
- That we can find the X_i in polynomial time

Minimum Bisection Approximation

Given graph $G = (V, E)$ and cost function $c : E \rightarrow \mathbb{R}^+$.

- 1 Interpret costs $c(e)$ as **capacities**
- 2 Solve oblivious routing on G , obtaining **trees** T_i
- 3 Find minimum **tree bisections** X_i for all trees T_i
- 4 Choose the X_i with **lowest** $c(\delta(X_i))$

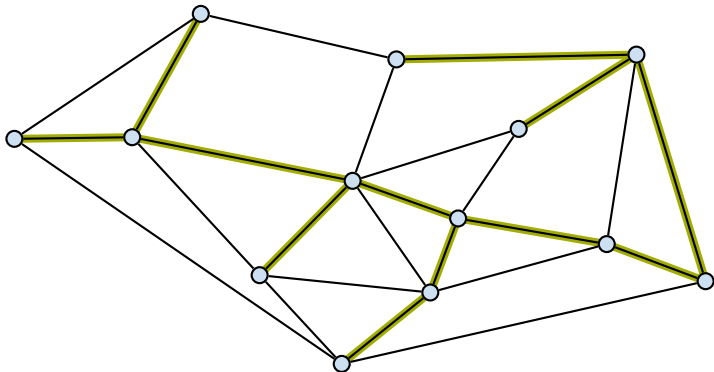
We have to show

- What the X_i actually are
- An $\mathcal{O}(\log n)$ -**approximation** guarantee
- That we can find the X_i in polynomial time

- Given a spanning tree T of G with an edge $e_T \in E_T$
- Define a new **cost function** c_T using tree splits

$$c_T(e_T) = C(e_T)$$

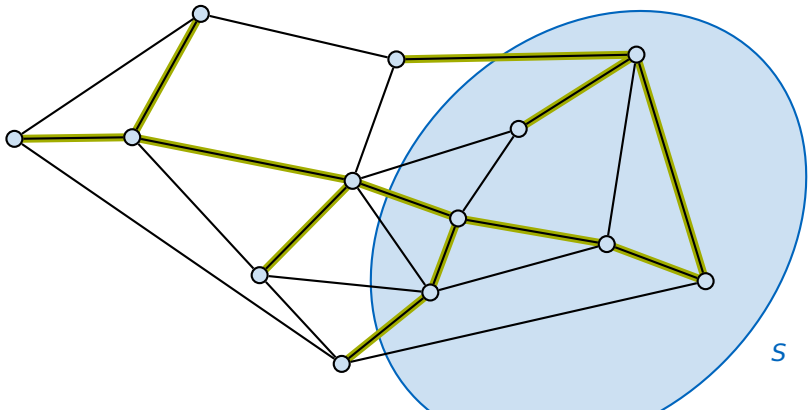
$$c_T(\delta(S)) = \sum_{\substack{e_T \in E_T: \\ e_T \in \delta(S)}} C(e_T)$$



- Given a spanning tree T of G with an edge $e_T \in E_T$
- Define a new **cost function** c_T using tree splits

$$c_T(e_T) = C(e_T)$$

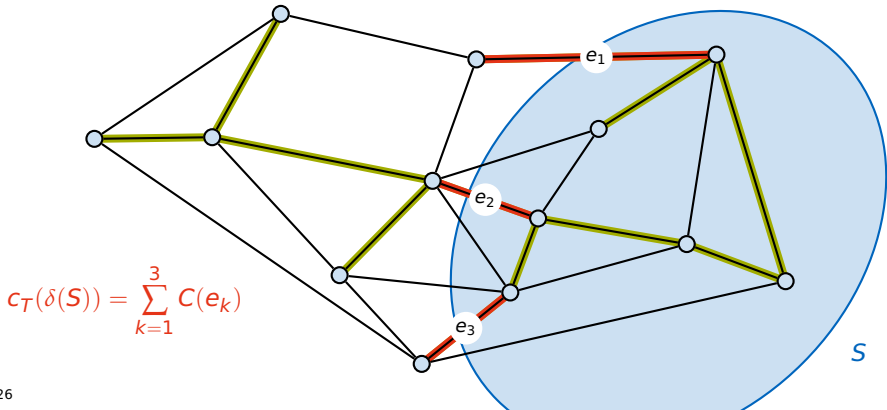
$$c_T(\delta(S)) = \sum_{\substack{e_T \in E_T: \\ e_T \in \delta(S)}} C(e_T)$$



- Given a spanning tree T of G with an edge $e_T \in E_T$
- Define a new **cost function** c_T using tree splits

$$c_T(e_T) = C(e_T)$$

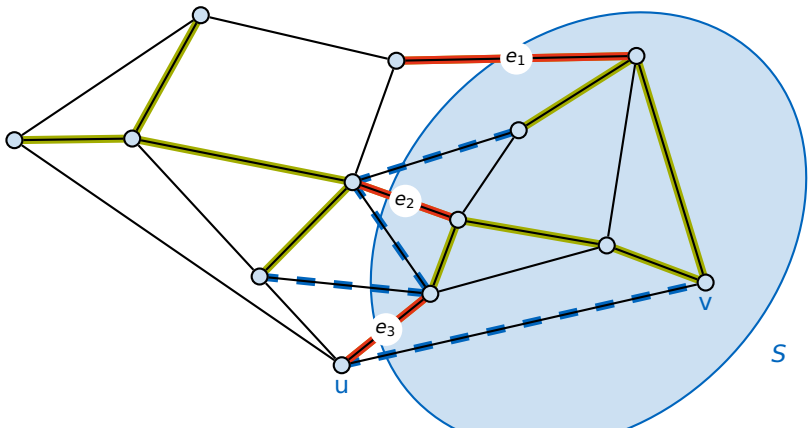
$$c_T(\delta(S)) = \sum_{\substack{e_T \in E_T: \\ e_T \in \delta(S)}} C(e_T)$$



Lemma

For any spanning tree T and any $S \subseteq V$ we have

$$c(\delta(S)) \leq c_T(\delta(S))$$



Lemma

Let $\{T_i\}$ be a solution to the *oblivious flow* problem on G .
Then for any $S \subseteq V$ we have

$$\sum_i \lambda_i c_{T_i}(\delta(S)) \leq \mathcal{O}(\log n) c(\delta(S))$$

- Remember from the primal program that for all $u, v \in V$

$$\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T) \leq \mathcal{O}(\log n) c_{uv}$$

- We sum up the inequalities for all $(u, v) \in \delta(S)$

Lemma

Let $\{T_i\}$ be a solution to the *oblivious flow* problem on G .
Then for any $S \subseteq V$ we have

$$\sum_i \lambda_i c_{T_i}(\delta(S)) \leq \mathcal{O}(\log n) c(\delta(S))$$

- We sum up the inequalities for all $(u, v) \in \delta(S)$
- This gives us

$$\sum_i \lambda_i \sum_{(u,v) \in \delta(S)} \sum_{\substack{e_T \in T_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T) \leq \mathcal{O}(\log n) c(\delta(S))$$

- We are done with the observation that

$$c_{T_i}(\delta(S)) = \sum_{\substack{e_T \in T_i: \\ e_T \in \delta(S)}} C_i(e_T) \leq \sum_{(u,v) \in \delta(S)} \sum_{\substack{e_T \in T_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T)$$

Minimum Bisection Approximation

Given graph $G = (V, E)$ and cost function $c : E \rightarrow \mathbb{R}^+$.

- 1 Interpret costs $c(e)$ as **capacities**
- 2 Solve oblivious routing on G , obtaining **trees** T_i
- 3 Find minimum **tree bisections** X_i for all trees T_i
- 4 Choose the X_i with **lowest** $c(\delta(X_i))$

- Let now X^*, X_i be the optimal solutions on G and the T_i . Then

$$\begin{aligned} \sum_i \lambda_i c(\delta(X_i)) &\leq \sum_i \lambda_i c_{T_i}(\delta(X_i)) \\ &\leq \sum_i \lambda_i c_{T_i}(\delta(X^*)) \\ &\leq \mathcal{O}(\log n) c(\delta(X^*)) \end{aligned}$$

- This also holds for the **best** X_i , giving an $\mathcal{O}(\log n)$ -**approximation**
- How to find the X_i ?